

3D Imaging from Video and Planar Radiography



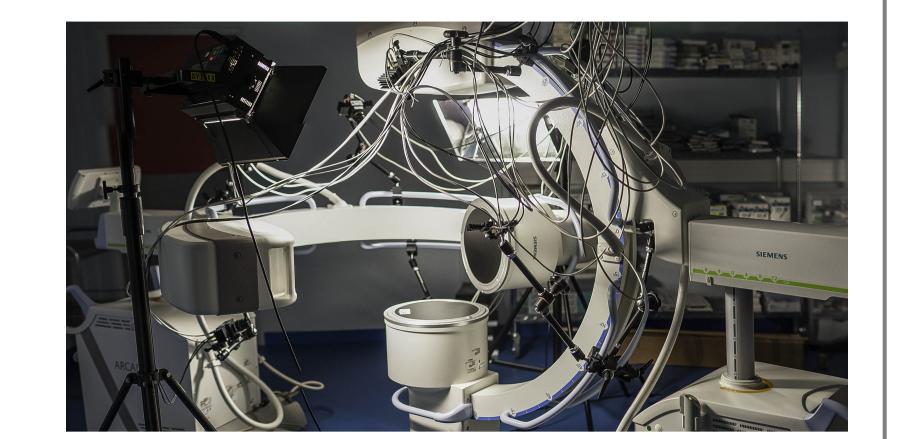
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KINOVIS Hybrid Capture Platform

Kinovis capture platform

- 10 video cameras (4 Mpix)
 - 3D surface motion
 - Up to 100fps
- 2 X-ray C-arms (1 Mpix)
- In-depth motion
- Up to 30 fps
- Low radiation dose Capture volume: 30x30x30cm



Motivation

Objectives

- Capture dense model of moving samples
- Study correlation between surface and in-depth structure motion

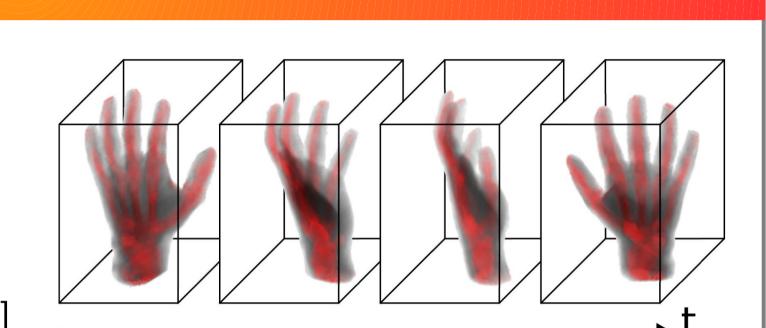
Benefits compared to regular CBCT

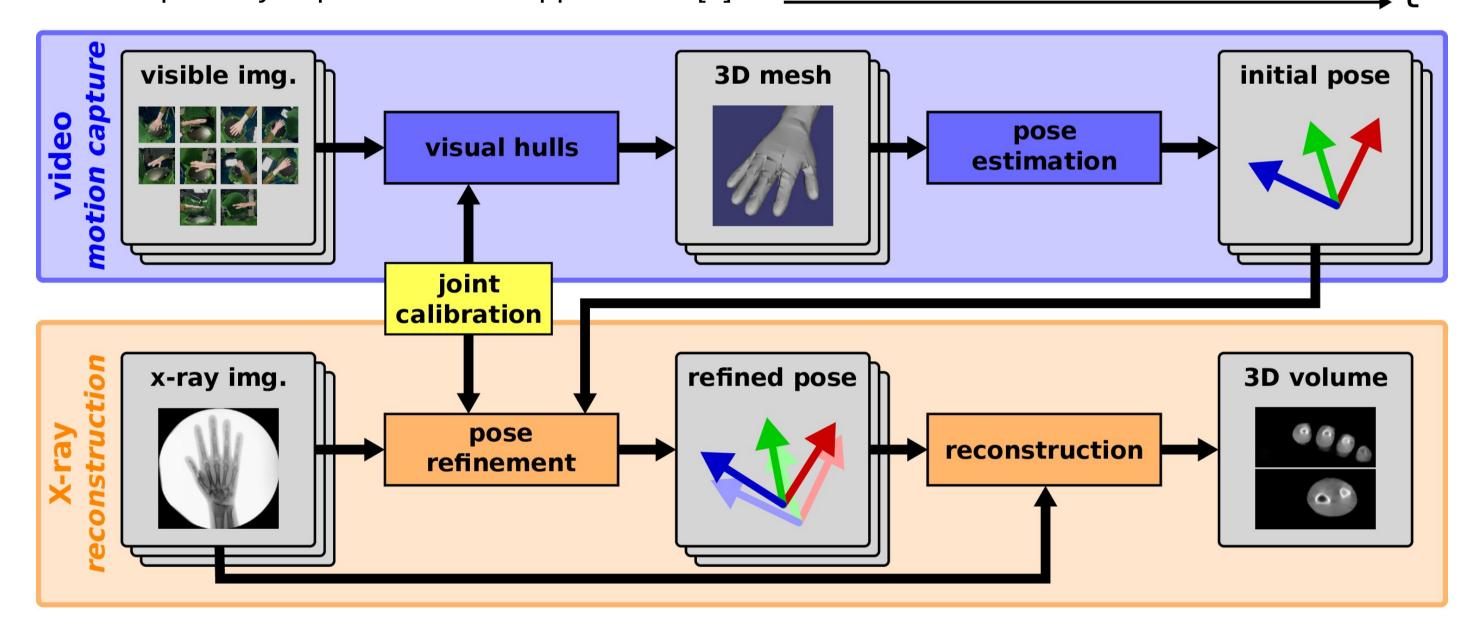
- Limit patient radiation
- Reduce costs
- Ability to capture motion

Proposed Approach

Overall idea

- Move sample rather than X-ray device
- Recover sample rigid motion using video
- Volumetric reconstruction from X-ray
- Generative image formation model
 - Inspired by super-resolution approaches [1]





Generative Image Formation Model

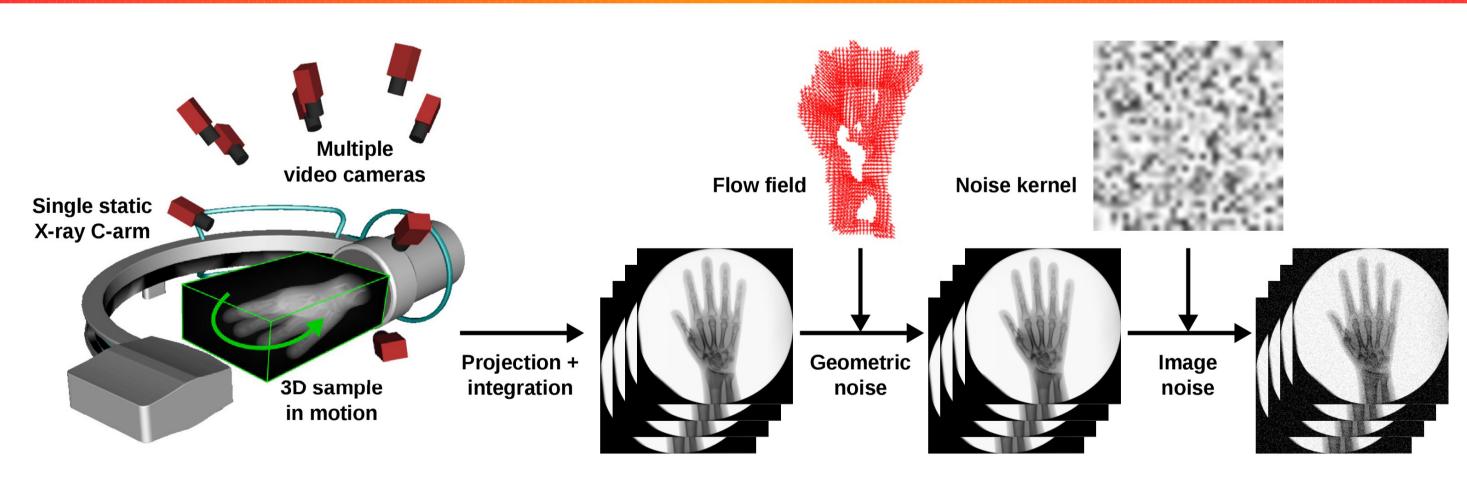


Image formation model composed of:

- Known projection/integration matrix
- 2D image noise (light source, amplifier, sensor, ...)
- 3D geometric noise (motion, projection, ...)

MAP estimation:

- Volumetric attenuation
- 2D & 3D noise parameters
- Regularisation: TV L₁ prior

Bayesian Model Estimation

Iterative independent estimation of:

- Attenuation given 2D & 3D noise using Iteratively Reweighted Least Squares (IRLS) with TV L₁
- 2D image Gaussian noise variance based on residual error (gamma distribution)
- 3D geometric warp based on residual optical flow

Video link

Acknowledgements

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References

[1] C. Liu and D. Sun. On Bayesian adaptive video super resolution. TPAMI 36(2), 346-360 (Feb 2014).

[2] J. Pansiot, L. Reveret, and E. Boyer. Combined Visible and X-ray 3D Imaging. MIUA, pp. 13-18, London, 2014.

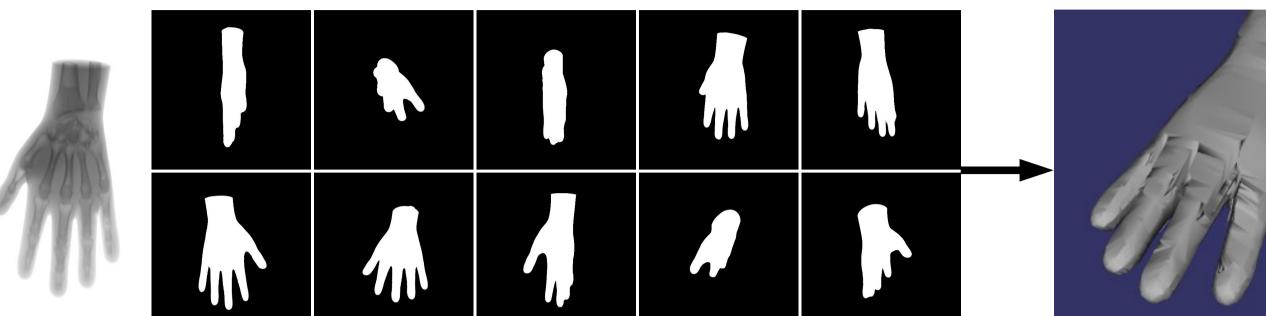
Simulated Forearm Phantom

Forearm phantom CT scan rendered as:

- 10 video silhouettes (thresholding)
- 1 X-ray image (raycasting)

Simulated motion

- Moved over 32 frames
- Rotation over ~180°



1 simul. X-ray

10 simulated video silhouettes 1 visual hull mesh

Results Without TV L₁ prior Without optical flow Ground truth CT Proposed method ART [2] 00 **RMS Error** 0.125 0.134 0.180 0.072 MI score 0.338 0.318 0.177 0.309

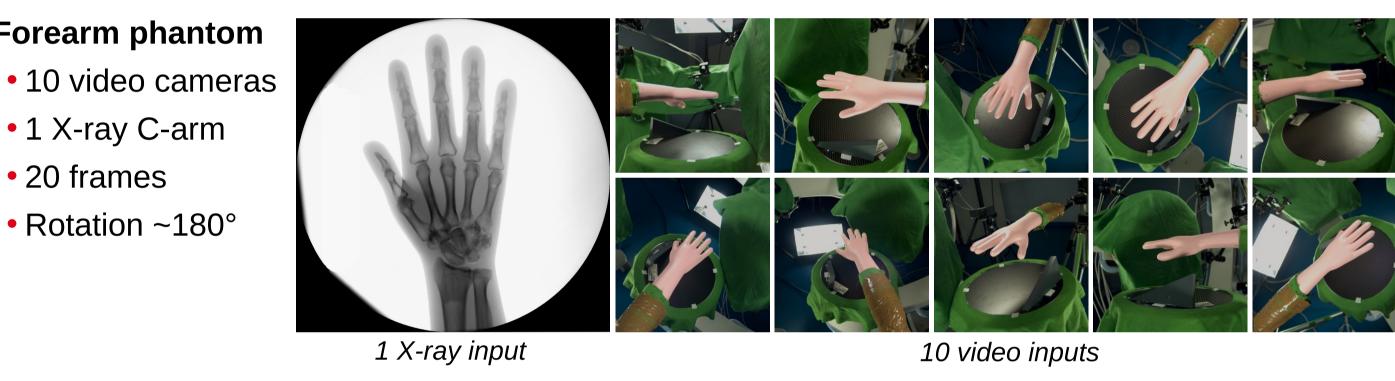
In-situ Forearm Phantom

Forearm phantom

- 1 X-ray C-arm

• 20 frames

Rotation ~180°



Results Without optical flow Ground truth CT Without TV L₁ prior ART [2] **Proposed method** N/A (failed) 0.146 0.137 0.094 MI score

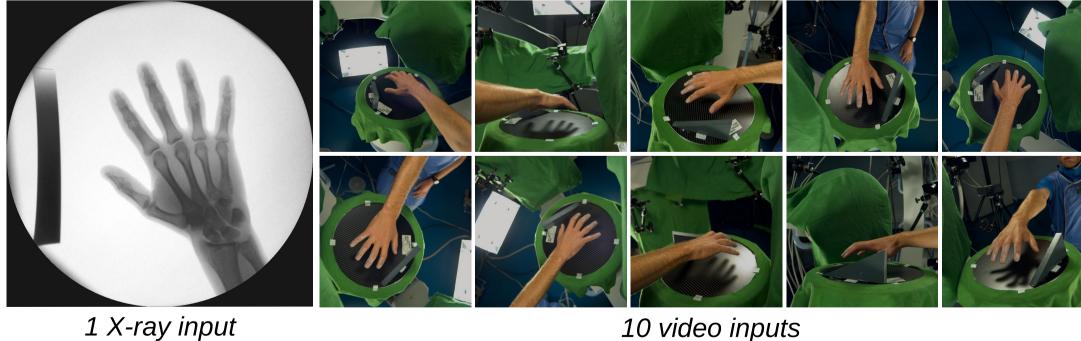
In-vivo Human Hand

In-vivo human hand data

- 10 video cameras (sensor: 4 Mpix utilised: 1MPix)
- 1 X-ray C-arm (1 Mpix)
- Volumetric resolution: 0.8mm/voxel

Actual motion

- Moved over 20 frames at 10 fps
- Free wrist rotation over ~180°
- Near-rigid



10 video inputs

Results Reduced TV L, prior Without TV L₁ prior Proposed method Without optical flow ART [2]

